## ADVANCED NUMERICAL METHODS

## DEGREE IN INDUSTRIAL TECHNOLOGY ENGINEERING

## JUNE 23, 2015

N.B.: The exam will be sat uninterruptedly (without a break) and will be marked over 24 points.

#### EXERCISE 1

#### (6 points)

(6 points)

A student wants to interpolate some function f(x) in the interval [1.74, 6.26] using 5 nodes. Working with 3 or more significant digits:

a) Calculate the nodes she will use to minimize the maximum absolute error in the interval. (1p)

In case 5 nodes were not enough, the student eventually decides to use 6, and evaluating f(x) on them she obtains the following table (rounded to 3 significant digits):

|    |   | $x_i$                 | 1.82       | 2.4                     | 3.42  | 4.58                      | 5.6       | 6.18      |               |
|----|---|-----------------------|------------|-------------------------|---|---------------------------|-----------|-----------|---------------|
|    |   | $f(x_i)$              | 0.844      | 0.309                   | -0.249  | -0.249                    | 0.309     | 0.844     |               |
| b) | Calculate the   | e table of            | difference | es.                     |   |                           |           |           | (1p)          |
| c) | Calculate the interpolation polynomial $p_3(x)$ of degree $\leq 3$ by the last four nodes. (1p) |                       |            |                         |   |                           |           |           |               |
| d) | ) Estimate $f(5.1)$ evaluating $p_3(x)$ optimally.  |                       |            |                         |   |                           |           | (1p)      |               |
| e) | Prove the ex<br>from the Ne   | pression<br>wton poly | ynomials o | e(z) = f[<br>of degrees | $x_0, x_1, \dots, x_n$<br><i>n</i> and <i>n</i> + | $x_n, z$ ] $\Pi(z)$<br>1. |           |           | (1p)          |
| f) | Estimate the error made in part d).   |                       |            |                         |   |                           |           | (0.5p)    |               |
| a) | Knowing th  | at the in             | ternolated | function                | was $f(x)$ :                                      | $=\cos(\pi x)$            | calculate | the error | actually made |

**g)** Knowing that the interpolated function was  $f(x) = \cos(\pi x)$ , calculate the error actually made in d), compare it with the estimation in f), and comment on the results. (0.5p)

## **EXERCISE 2**

Let  $I = \int_{1}^{3} f(x) dx$ . Working with 5 decimals:

a) Apply the compound midpoint rule to estimate *I* from the data in this table: (1p)

$$x_i$$
1.251.752.252.75 $f(x_i)$ 0.53710.19000.03840.0044

b) Knowing that the error term of the compound midpoint rule is

$$E = \frac{b-a}{6}h^2 f''(\xi) \quad \text{for some } \xi \in (a,b)$$

and that  $|f''(x)| \le 0.89617 \quad \forall x \in \mathbb{R}$ , find an upper bound of the absolute error made in a). (1p)

- c) Find how many subintervals will guarantee that the error does not exceed  $\varepsilon = 0.005$ . (1p)
- d) Knowing that the data above correspond to  $f(x) = e^{-x^2}(x^2 + 1)$ , explain what kind of Gaussian quadrature you would use to approximate *I*, and apply it to obtain *I* with the precision indicated in part c). (Use the nodes and coefficients of the final Appendix.) (2.5p)
- e) According to the results of c) and d), what rule guarantees the required precision with less computational cost: the compound midpoint rule or the Gaussian one of d)? Explain. (0.5p)

#### **EXERCISE 3**

#### (6.5 points)

The movement of the system of springs of the figure in the Appendix is governed by the system:

$$\begin{cases} m_1 \frac{d^2 y_1}{dt^2} = -(k_1 + k_2) y_1 + k_2 y_2 \\ m_2 \frac{d^2 y_2}{dt^2} = k_2 y_1 - k_2 y_2 \end{cases}$$

where  $y_1$ ,  $y_2$  are the displacements of the masses  $m_1$ ,  $m_2$  from their equilibrium positions, and  $k_1$ ,  $k_2$  are the springs' elasticity constants.

For  $m_1 = m_2 = 1$ ,  $k_1 = 1$ ,  $k_2 = 2$ and the initial conditions:  $y_1(0) = 1$ ,  $y'_1(0) = 0$ ,  $y_2(0) = 1$ ,  $y'_2(0) = 0$ , working with 2 decimals:

- a) Transform the system of differential equations above into one of order 1. (1p)
- **b)** Estimate the displacements  $y_1$ ,  $y_2$  at t = 1 with the Runge-Kutta method of order 4. (3p)
- c) Knowing that the characteristic polynomial of the Jacobian matrix associated to the system obtained in part a) is  $p(\lambda) = \lambda^4 + 5\lambda^2 + 2$ , and that the absolute stability regions of the RK1, RK2, RK3, RK4 methods are those shown in the figure in the Appendix, is the step size h=1adequate to solve the problem using RK4? Justify the answer. (2p)
- d) Say which of the methods in the figure are adequate, and which are not, to solve the problem with step size h = 0.5. (0.5p)

#### **EXERCISE 4**

One wants to estimate  $f^{(3)}(z)$  using equally-spaced nodes from  $x_0 = z$  to its right.

- a) What is the least number of nodes one needs to use?
- b) Using four nodes (from  $x_0 = z$  to  $x_3 = z+3h$ ), obtain the numerical differentiation formula using Taylor series expansions (without needing to obtain its error term). (2p)
- c) Knowing that the error term can be written in the form  $E = -3f^{4}(\xi)h/2 + O(h^2)$  for some  $\xi \in [z, z+3h]$ , estimate the optimal distance between nodes  $h_{opt}$ . Write the result in terms of  $M \ge |f^{4}(\xi)|$  and of  $\varepsilon \ge |f_i \overline{f_i}|$ . (1p)

For  $f(x) = 2\sin(2x)$ ,  $z = \pi/12$ , and for Matlab's usual arithmetic (considering  $\varepsilon = 10^{-16}$ ):

- d) Estimate numerical values of  $h_{opt}$  and of the expected upper bound of the absolute error. (1p)
- e) To calculate these values we have accepted some assumptions that are not exactly satisfied. Say at least one. (0.5p)
- f) Since we have accepted assumptions that are not quite satisfied, one may want to check the estimations of part d) experimentally. The final figure in the Appendix has  $10^7$  points. Each one has as abscissa some random value of *h*, and as ordinate the absolute error made when estimating  $f^{(3)}(z)$  using that value of *h*. Explain if your results in d) are good or not. (0.5p)

See Appendix in separate sheet

## (5.5 points)

(0.5p)

# Appendix:

| rodes and weights for part dy of excletise 2. |   |   |  |  |  |  |  |
|---|---|---|--|--|--|--|--|
| n = 1   | $x_0 = -3^{-1/2},  x_1 = 3^{-1/2}$  | $A_0 = A_1 = 1$   |  |  |  |  |  |
| n=2   | $x_0 = -0.77460,  x_1 = 0,  x_2 = 0.77460$  | $A_0 = A_2 = 0.55556,  A_1 = 0.88889$                               |  |  |  |  |  |
| <i>n</i> =3                                   | $x_0 = -0.86114,  x_1 = -0.33998,  x_2 = 0.33998,  x_3 = 0.86114$                             | $A_0 = A_3 = 0.34785,$<br>$A_1 = A_2 = 0.65215$                     |  |  |  |  |  |
| <i>n</i> =4                                   | $x_0 = -0.90618,  x_1 = -0.53847,  x_2 = 0,$<br>$x_3 = 0.53847,  x_4 = 0.90618$               | $A_0 = A_4 = 0.23693,$<br>$A_1 = A_3 = 0.47863,  A_2 = 0.56889$     |  |  |  |  |  |
| n=5   | $x_0 = -0.93247, x_1 = -0.66121, x_2 = -0.23862, x_3 = 0.23862, x_4 = 0.66121, x_5 = 0.93247$ | $A_0 = A_5 = 0.17132,  A_1 = A_4 = 0.36076, \\ A_2 = A_3 = 0.46791$ |  |  |  |  |  |

Nodes and weights for part d) of exercise 2:

Figures of the exercise of Initial Value:





